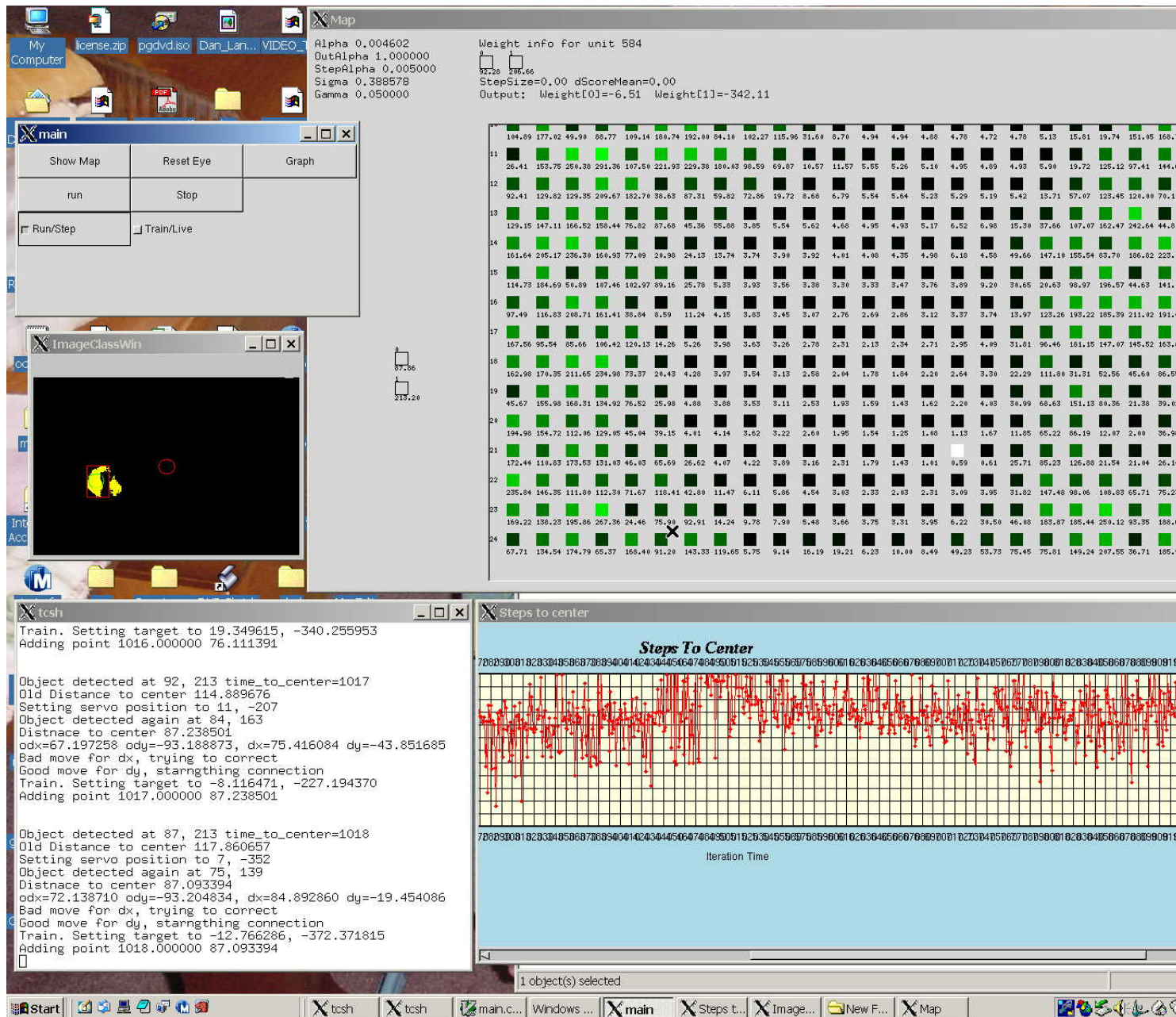


Software

Written by Lior

Thursday, 27 January 2011 23:14 -



The software is written in c++ using Gtk+ and gnome as the gui interface. The sofml is derived from [sofml](#) with a few modification. The main modification is rewiring the software to be object oriented as well as the addition of displaying the map in a graphical format. The vision processing is implemented using Intel [OpenCV](#) libraries with the addition of [CMVision](#) to get the coordinates of a color blob.

Software

Written by Lior

Thursday, 27 January 2011 23:14 -

The software is available from [here](#). It will need Gnome/Gtk+ libraries and [GtkPlot](#) to compile.

The IsoPod software is written in Forth and for now it just moves the servos to a given position.

[SOFT_ARM_SOFTWARE](#) [ISOPOD ARM Software](#)